



BathySurvey

A Trimble Access hydrographic survey module

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1. Introduction

BathySurvey is a plugin for the Trimble Access software. It's a hydrographic software package capable of communicating via a serial port with an echo sounder. At the moment the following echo sounders are supported:

- Odom Echotrac CVM
- Odom Echotrac CV100
- Ohmex Sonarmite
- NMEA DBS
- NMEA DBT

BathySurvey adds a depth to a GNNS position record. A custom stylesheet is delivered with the software to convert the Trimble Access Job file to a comma separated ASCII file.

When using the Odom Echotrac CVM/ CV100 or Ohmex Sonarmite the settings of the echo sounder can be changed. The NMEA protocols are just for reading the depth(s) from an NMEA string.

A barcheck wizard can determine the transducer depth and sound velocity.





2. Installation

After installing BathySurvey via the Trimble Access Installation Manager the BathySurvey icon will appear on the main screen of Trimble Access.







3. Main Screen

The Bathy Survey main screen has four buttons and one soft key to choose the correct echo sounder device and communication parameters. Always start by checking the device settings.







4. Device

Choose the correct echo sounder and communication settings.

>	-> O	? – X
Device:		
Odom Echotrac	CVM 🔽	
Controller port:	Baud rate: 9600 -	7
Data bits:	Stop bits:	
8	1	
Parity:	Flow control:	<u>M</u> ap
None 🔻	None	M <u>e</u> nu
		F <u>a</u> vorites
		Switch to
Esc		Enter





5. Jobs

Has the same functionality as the Jobs menu in General Survey.

📡 Jobs	-> < - ×
New job	Properties of job
Open job	Copy between jobs
Review job	Import / Export
Point manager	
QC Graph	
Мар	
Back	Accept





6. Settings Odom Echotrac

After starting the settings menu from the main screen BathySurvey will query the echo sounder settings. This will take a couple seconds. After the message "Updating Finished" appears you will be able to change the settings.

The maximum operating depth range of the echo sounder. Valid parameters from 0 to 12000 meters. The default is 45 meter.

Blanking level to digitizer. Digitizer will not track anything above this depth. Valid parameters from 0 to 12000 meters. The default is 0 meter.

Minimum depth alarm. The echo sounder will sound an alarm if the depth is shallower than this depth. Valid parameters from 0 to 30 meters. The default is 0 meter.

The 'Defaults' button will reset all the echo sounder parameters. Note that this will set the communication baud rate to 19200.

EchoTrac	? – ×
Communication Updating Finished	
System Maximum Depth (m): Blanking (m): 45	Map
Min. Depth Alarm (m): 0 1/6	M <u>e</u> nu F <u>a</u> vorites S <u>w</u> itch to
Esc Defaults	Enter





When set to 0 the echo sounder pings at the highest rate for that depth. When set from 1-20 the echo sounder will sound up to a maximum to that ping rate/sec as long as the water depth allows it. Valid parameters from 0-20. Default is 0.

Echo Alarm. When switched on the echo sounder will sound an alarm when the depth is shallower the the set minimum depth.

Standby Bit. When set to On the echo sounder will go to standby when turned on.

High frequency channel operating frequency. Valid parameters from 12 to 1000 kHz. Default is 200 kHz.

High frequency channel pulse width in cycles. Valid parameters from 1 to 256. Default is 20.

SchoTrac	-) 🖉 🛛 ? 💶 🗙
Ping Rate (0=auto):	Echo Alarm: Off	
Standby Bit:		
Channel 1		
Frequency (kHz):	Pulse Width (cycles): <u>M</u> ap
200	20	M <u>e</u> nu
		P/6 Favorites
		Switch to
Defaults		Enter





Low frequency channel operating frequency. Valid parameters from 8 to 200 kHz. Default is 24 kHz.

Low frequency channel pulse width in cycles. Valid parameters from 1 to 256. Default is 20.

Draft of high frequency transducer. Valid parameters from 0 to 1500 centimeters. Default is 0 centimeter.

Index error of high frequency transducer. (Opposite of draft) Valid parameters from 0 to 1500 centimeters. Default is 0 centimeter.

EchoTrac	- > Ø	? – ×
Channel 2		
Frequency (kHz):	Pulse Width (cyles): 20	
Channel 1		
Draft (cm):	Index (cm):	<u>M</u> ap
	0	M <u>e</u> nu
	2/6	F <u>a</u> vorites
	3 , v	Switch to
Esc Defaults		Enter





Draft of low frequency transducer.

Valid parameters from 0 to 1500 centimeters. Default is 0 centimeter.

Index error of low frequency transducer. (Opposite of draft) Valid parameters from 0 to 1500 centimeters. Default is 0 centimeter.

The Sound Velocity.

Valid parameters from 1370 to 1700 m/s. Default is 1500 m/s.

EchoTrac		-> ⊘	? – ×
Channel 2 Draft (cm):	Index (cm): 0		-*
Calibrate Sound Velocity (m/s): 1500			Map
			Menu
		1/6	Favorites
		~	Switch to
Esc Defaults			Enter





Function and baud rates of the serial ports.

EchoTrac 🔊 📀	? – ×
COM 1	
Echotrac DBT ▼ 9600 ▼	- T
Remote:	<u>M</u> ap
	M <u>e</u> nu
	F <u>a</u> vorites
	Switch to
Esc Defaults	Enter





EchoTrac 🧈 🕗	? – ×
COM 3	•
NMEA: Baud Rate: No GPS input ▼ 9600 ▼	Y
COM 4	
Heave: Baud Rate:	Map
Heave Turned Off 9600	M <u>e</u> nu
C/6	F <u>a</u> vorites
	Switch to
Esc Defaults	Enter





7. Settings Ohmex Sonarmite

With the 'Toggle' button you can switch between the different outputs of the Sonarmite. When you reach the SYS output, the sound velocity (7^{th} field) can be changed with the 'up' and 'down' buttons.

SonarMite	? – ×
Version SonarMite v3.02(c)2011 LYMTECH	
Output SYS> 2 0 65 65 0 0 1500 10.4 0	Maria
Toggle	 M <u>e</u> nu
	F avorites
	Switch to
Esc	Enter





8. Barcheck Odom Echotrac

You can use the barcheck wizard to determine the transducer draft and sound velocity. Choose the channel to calibrate.

Bar Check Wizard	? – ×
Primary Channel Bar Check Channel: Channel 1 ▼ Channel 1 Channel 2	
	<u>M</u> ap
	M <u>e</u> nu
	F avorites
	Switch to
Can.	Next





Enter the initial sound velocity to get an approximate depth. The default is 1500 m/s. Enter the draft of the transducer as physically measured from water surface to bottom of transducer.

Bar Check Wizard	? – ×
Sound Velocity (m/s) Enter initial sound velocity (m/s): 1500	•
Channel 1 Enter draft (cm) of transducer:	<u>M</u> ap
	M <u>e</u> nu
	F <u>a</u> vorites
	Switch to
Back	Enter





Deploy the bar below the transducer at a depth of less than 5 meters and enter the bar's known depth. Set the width of the digitizer gate to eliminate returns other than the bar. Once you have a digitized depth from the bar press calculate to get the draft and index.

Bar Check Wizard	? – X
Enter the bar's known depth (m):	
1	Ψ.
Digitized Depth (m): 3.01 Calculate	
Adjust index (cm):	<u>M</u> ap
	M <u>e</u> nu
50	F <u>a</u> vorites
	Switch to
Back	Next





Deploy the bar below the transducer to the deepest calibration depth and enter the bar's known depth. Set the width of the digitizer gate to eliminate returns other than the bar. Once you have a digitized depth from the bar press calculate to get the sound velocity. If you are doing your survey using RTK, make sure to check the 'Reset Draft en Index' checkbox. The draft and index parameters will then be set back to zero.

😰 Bar	Check Wiz	ard			- > (2	? -	- 🗙
Enter the I	oar's known dept	th (m):	Set width (5	(m) of digitizer g	ate:			100%
Digitized D 11.00	epth (m):		Calculate]			ji T	14
Adjust sou	nd velocity (m/s)):	Reset Draft	t en Index:			-	2.000
							M	ap
							Me	enu
							Favo	orites
							S <u>w</u> it	ch to
	RTK H:0.008m V:0.010m 🗸							
Back							En	ter





9. Barcheck NMEA

Deploy the bar below the transducer at the shallowest calibration depth and enter the transducer draft.

Draft = Bar Depth – Digitized Depth

Bar Check Wizard	? – ×
Shallowest depth (m) Enter draft (m) of transducer: 0.50	-*
Digitized Depth (m): 20.1	
	<u>M</u> ap
	M <u>e</u> nu
	F <u>a</u> vorites
	Switch to
Can.	Enter





Deploy the bar below the transducer to the deepest calibration depth and enter the bar's known depth and the sound velocity as setup in your echo sounder. Once you have a digitized depth from the bar press calculate to get the sound velocity. When using NMEA output from an echo sounder you can use the calculated sound velocity to change the sound velocity setting in your echo sounder.

Bar Check Wizard	? – ×
Deepest depth (m) Bar Depth (m): Digitized Depth (m): 20.2 ▶ 20.0	
Enter initial sound velocity (m/s): 1500	
Calculated sound velocity (m/s): 1470	Map
	M <u>e</u> nu
	F <u>a</u> vorites
Calculate	Switch to
Back	Save





10. Online

The Online screen shows a side view of the bottom profile. When a second frequency is used it will become visible in light yellow. The lower frequency is drawn behind the higher frequency. At the bottom the depth and speed are shown. When using a Sonarmite the battery voltage and quality indicator are also shown.







11. Gain/ TX

To set the gain and Tx power for the Odom Echotrac.

🖗 Gai	n/ TX Powei	Г			-> 0	? -	- ×
Channe Gain, 0-2 255	I 1 56, 256 = auto:		Tx Power, 6	0-12, 0 = auto:			100% 15
Channe Gain, 0-2 255	1 2 56, 256 = auto:		Tx Power, 6	0-12, 0 = auto:		7	?
						M	ap
						M	enu
						Favo	orites
						S <u>w</u> it	ch to
		Depth high: 1	1.05 m, low: 0	.00 m, v: 0.00 n	n/s		
Esc						En	iter





12. Scale

To set the bottom side view plot scale and the speed units.

🖗 Sca	le 🕘 🕗	? – ×
Scale Min: 0 Units Speed: m/s ▼ m/s kn	Max: 25	100%
		<u>M</u> ap
		M <u>e</u> nu
		F <u>a</u> vorites
		Switch to
	No survey PDOP:1.3	
Esc		Enter





13. Record

Pressing 'Record' from the Online screen will start a continues topo measurement.

Sol 🧐	ntinuous topo)			->		? – ×
Method: Fixed ti Antenna h 2.358m Measured	me	 d): 	Time interv	/al:			100%
Bottom	of quick rele	ease 💌	Umis				₹ 2.000
50	: name:		Code: 1				
							<u>M</u> ap
							M <u>e</u> nu
							F <u>a</u> vorites
							S <u>w</u> itch to
_	D	epth high: 11	.04 m, low: 0.0	0 m, v: 0.00 m/s	S	×	
Esc		eBubble		Options			Enter